

Palm grip B 3

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The palm grip B 3 is an actuating element for our multi-axis controller V 8, VV 8, V 6, VV 5. It can also be used as an actuating element for hydraulic drives.

Push buttons, rocker switches, e.t.c., can also be fitted to suit appropriate requirements.

The drives with Potentiometer PA 11/12 and PA 13 realised the direction 11-12 resp. 13-14 (3. resp. 4 axis) on our multi-axis controllers.

The palm grip has a highly flexible single wire $0.1\ mm^2\ x\ 450\ mm\ long$.

The mounting piece for the drive rod can be supplied with a tapped hole 12 or 10 mm (standard = 12 mm). The palm grip B 3 is made of PPO plastic and is black in color.

Contact complement 0,5 A 110 V AC 15 res. 1,5 A 24 V DC 13 I min > 0,2 mA 2 V DC 12 Gold plated for max. load of 0,12 Watt (standard) or I max < 300 mA 0,4 V DC 12 max. capacity 0,12 Watt do not exceed! I min >0,2 mA 2 V DC 12 max. contact reliability for very low current (special)

Permissible ambient temperature

Operating -40°C to +60°C Storage -50°C to +80°C Storage

Climate resistance Damp heat constant Damp heat cyclic Degree of protection front

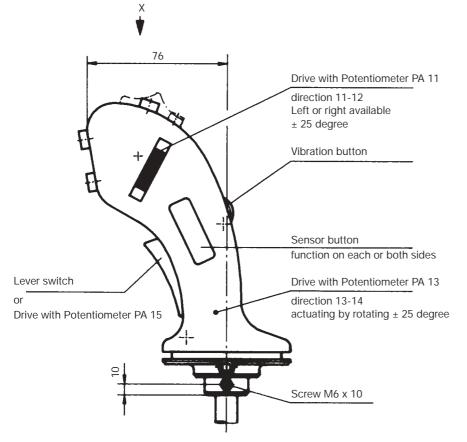
DIN IEC 68 part 2-3 DIN IEC 68 part 2-30 IP 65 IEC 529 DIN 40050

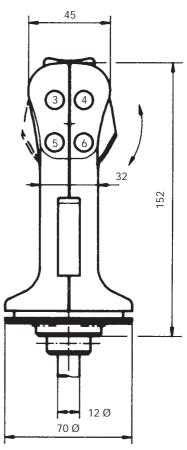
Pos.			Туре	Weight gramm	Price EURO
1	Palm grip with mounting piece for control-handle			200	
2	Push button 1 NO	installed Pos. 1, 2, 3, 4, 5, 6	D	20	
3	Rocker switch tast-0-tast T-0-T 2 NO	installed Pos. 1 + 2	W	30	
4	Rocker switch tast-0-rest T-0-R 2 NO	installed Pos. 1 + 2	W	30	
5	Rocker switch rest-0-rest R-0-R 2 NO	installed Pos. 1 + 2	W	30	
6	Lever switch 1 NO		K	30	
7	Sliding switch tast-0-tast T-0-T 2 NO	installed Pos. 13 + 14	ST	40	
8	Sliding switch rest-0-rest R-0-R 2 NO	installed Pos. 13 + 14	SR	40	
9 10	Push button with 2 steps Latch for mechal 4 contacts arrangement MS 212 look cata		ZD	90	
11	Drive with potentiometer PA 11 actuating by rocker wheel installed Pos. left or right with spring return in the centre position 1 conductive-plastic-potentiometer T 375 with centre tap Linear 10 ⁷ switching cycles resistance 2 x 5 kOhm 0,5 Watt wiper-current max. 1 mA 2 directions-contacts Drive with Potentiometer PA 12 actuating by push button (details exactly PA 11) installed Pos. 11 + 12		PA 11	90	
12			PA 12		
13	Drive with Potentiometer PA 13 actuating by rotating palm grip left resp. right with spring return in the centre position 1 conductive-plastic-potentiometer T 375 with centre tap Linear 10 ⁷ switching cycles resistance 2 x 5 kOhm 0,5 Watt wiper current max. 1 mA 2 direction-contacts		PA 13	90	
15	Drive with Potentiometer PA 15 actuating by lever switch with spring return in 0-position 1 conductive-plastic potentiometer T 375 Linear 10 ⁷ switching cycles resistance 5 kOhm 0,5 Watt wiper current max. 1 mA 1 direction-contact		PA 15	90	
20	Vibrator button actuating through solenoid 24 V DC impulse signal 100% duty cycle factor		V	60	
21 22 23	Sensor button function on each or both sides with a regulator electronic board EY / 42-10 24 V DC (separate)		SE	20	
30 31 32 33	Bellow for palm grip B3 drawing No. KMD 109 Front plate with 4 screws M5 x 15 (for mounting the bellow) drawing No. KBF 321 required for multi-axis controller V 6, VV 5				

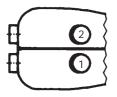


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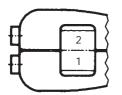




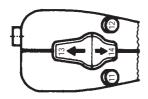
view X

Edition: push button

Edition:
Vibrator button only one
Drive with Potentiometer PA 13 version
Drive with Potentiometer PA 15 possible

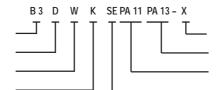


Edition: Rocker switch (installed Pos. 3, 4 inapplicable)



Edition:
Sliding switch installed Pos. 13, 14
installed Pos. 1, 2, 4, 6 inapplicable
Drive with Potentiometer PA 12 direction 11 - 12 installed Pos. 11, 12
PA 11 inapplicable
Pushbutton with 2 steps ZD installed Pos. 11 - 12
PA 11, 12 inapplicable

Example for type-sign
Palm grip
Push button
Rocker switch
Lever switch



Special please to describe
Drive with Potentiometer PA 13
Drive with Potentiometer PA 11
Sensor button