



The palm grip B9 has different equipment options for many requirements. It is compatible with our multi-axis controller or mounted on hydraulic drives. The palm grip has a highly flexible single wire $(0,1 \text{ mm}^2, 450 \text{ mm long})$. The mounting piece for the drive rod can be supplied with a tapped hole 12 mm (standard) or 10 mm.

Technical data

Operating temperature -40°C to +85°C

Degree of protection IP54

Contact complement 1,5A 24 V DC13



Example В9 -2D ΚT A13 **PA11 PA13** -X **Basic unit** В9 Palm grip Digital actuating element D Push button Colour: red, black, yellow, green, blue, white KT Cross switch T-0-T / T-0-T KR Cross switch R-0-R / R-0-R A11 Rocker switch T-0-T Pos. 11 + 12 A11 Rocker switch R-0-R Pos. 11 + 12 A13 Rotary grip T-0-T **Analog actuating element** V21 Hall-minijoystick (see page 45) Output 0,5...2,5...4,5 V inverse dual PA11 Rocker analog Pos. 11 + 12 Potentiometer T394 2 x 5 kOhm with direction contacts H11 Rocker analog Pos. 11 + 12 Hall-Potentiometer Output 0,5...2,5...4,5 V inverse dual PA13 Rotary grip

Special model

H13

X Special / customer specified

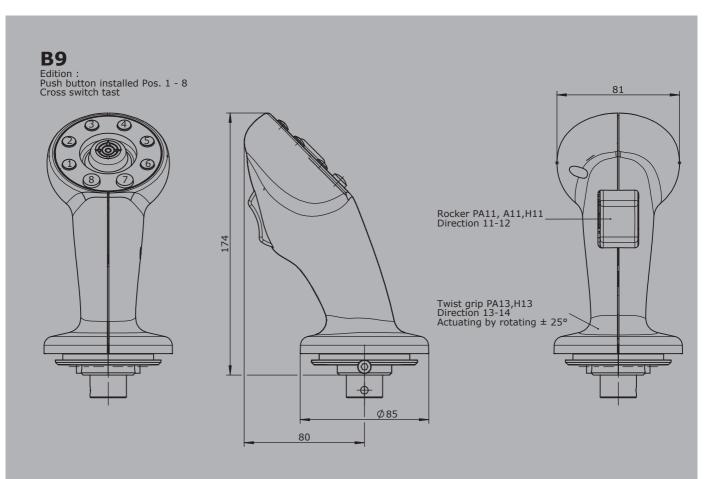
Output 0,5...2,5...4,5 V inverse dual

Hall-Rotary grip

Potentiometer T375 2 x 5 kOhm with direction contacts

Attachments		
Z01	Bellow KMD 109	10300009
Z02	Bellow KMD 190	10300093
Z03	Rosette KBF 905 with 4 screws M5x15 necessary for bellow KMD 190	5209900404





Edition:
Push button installed Pos. 1 - 8
Multi-axis controller V21

