Integrated Silicon Pressure Sensor On-Chip Signal Conditioned, Temperature Compensated and Calibrated

The MPXV4115V series piezoresistive transducer is a state-of-the-art monolithic silicon pressure sensor designed for a wide range of applications, particularly those employing a microcontroller with A/D inputs. This transducer combines advanced micromachining techniques, thin-film metallization and bipolar processing to provide an accurate, high-level analog output signal that is proportional to the applied pressure/vacuum. The small form factor and high reliability of on-chip integration make the Motorola sensor a logical and economical choice for the automotive system designer. Figure 1 shows a block diagram of the internal circuitry integrated on a pressure sensor chip.

Features

- 1.5 % Maximum error over 0° to 85°C
- Temperature Compensated from -40° + 125°C
- Ideally Suited for Microprocessor or Microcontroller-Based Systems
- Durable Thermoplastic (PPS) Surface Mount Package

Application Examples

- Vacuum Pump Monitoring
- Brake Booster Monitoring

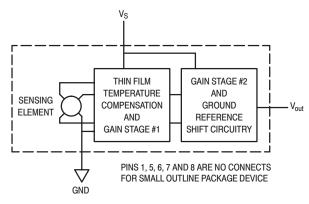


Figure 1. Fully Integrated Pressure Sensor Schematic

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INTEGRATED
PRESSURE SENSOR
-115 to 0 kPa (-16.7 to 2.2 psi)
0.2 to 4.6 V OUTPUT

SMALL OUTLINE PACKAGE



MPXV4115VC6U CASE 482A



MPXV4115V6U CASE 482

PIN NUMBER					
1	N/C	5	N/C		
2	V _S	6	N/C		
3	Gnd	7	N/C		
4	V _{out}	8	N/C		

NOTE: Pins 1, 5, 6, 7, and 8 are internal device connections. Do not connect to external circuitry or ground. Pin 1 is noted by the notch in the lead.

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MAXIMUM RATINGS(NOTE)

Parametrics	Symbol	Value	Unit
Maximum Pressure	P _{max}	400	kPa
Storage Temperature	T _{stg}	-40 to + 125	°C
Operating Temperature	T _A	-40 to + 125	°C

NOTE: Exposure beyond the specified limits may cause permanent damage or degradation to the device.

OPERATING CHARACTERISTICS ($V_S = 5 \text{ Vdc}$, $T_A = 25^{\circ} \text{ C}$ unless otherwise noted. Decoupling circuit shown in Figure 3 required to meet electrical specifications.)

Characteristic	Symbol	Min	Тур	Max	Unit
Pressure Range (Differential mode, Vacuum on metal cap side, Atmospheric pressure on back side)	P _{OP}	-115	_	0	kPa
Supply Voltage ⁽¹⁾	Vs	4.75	5	5.25	Vdc
Supply Current	Io	_	6.0	10	mAdc
Full Scale Output ⁽²⁾ (0 to 85° C) (Pdiff = 0 kPa) ²	V _{FSO}	4.535	4.6	4.665	Vdc
Full Scale Span ⁽³⁾ (0 to 85° C) @Vs = 5.0 V	V _{FSS}		4.4		Vdc
Accuracy ⁽⁴⁾ (0 to 85° C)		_	_	1.5%	%V _{FSS}
Sensitivity	V/P	_	38.26	_	mV/kPa
Response Time (5)	t _R	_	1.0	_	ms
Output Source Current at Full Scale Output	Io	_	0.1	_	mAdc
Warm-Up Time (6)	_	_	20	_	ms
Offset Stability (7)		_	±0.5	_	%V _{FSS}

NOTES

- 1. Device is ratiometric within the specified excitation voltage range.
- 2. Full-scale output is defined as the output voltage at the maximum or full-rated pressure.
- 3. Full—scale span is defined as the algebraic difference between the output voltage at full—rated pressure and the output voltage at the minimum—rated pressure.
- 4. Accuracy is the deviation in actual output from nominal output over the entire pressure range and temperature range as a percent of span at 25° C due to all sources of errors, including the following:
 - Linearity: Output deviation from a straight line relationship with pressure over the specified pressure range.
 - Temperature Hysteresis: Output deviation at any temperature within the operating temperature range, after the temperature is

cycled to and from the minimum or maximum operating temperature points, with zero differential

pressure applied.

• Pressure Hysteresis: Output deviation at any pressure within the specified range, when this pressure is cycled to and from

minimum or maximum rated pressure at 25°C.

TcSpan: Output deviation over the temperature range of 0° to 85°C, relative to 25°C.

• TcOffset: Output deviation with minimum pressure applied, over the temperature range of 0° to 85°C, relative

to 25°C.

- 5. Response Time is defined as the time for the incremental change in the output to go from 10% to 90% of its final value when subjected to a specified step change in pressure.
- 6. Warm-up Time is defined as the time required for the product to meet the specified output voltage after the pressure has been stabilized.
- 7. Offset Stability is the product's output deviation when subjected to 1000 cycles of Pulsed Pressure, Temperature Cycling with Bias Test.

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ON-CHIP TEMPERATURE COMPENSATION, CALIBRATION AND SIGNAL CONDITIONING

The performance over temperature is achieved by integrating the shear–stress strain gauge, temperature compensation, calibration and signal conditioning circuitry onto a single monolithic chip.

Figure 2 illustrates the gauge configuration in the basic chip carrier (Case 482). A fluorosilicone gel isolates the die surface and wire bonds from the environment, while allowing the pressure signal to be transmitted to the silicon diaphragm.

The MPXV4115V series sensor operating characteristics are based on use of dry air as pressure media. Media, other than dry air, may have adverse effects on sensor performance and long–term reliability. Internal reliability and qualification test for dry air, and other media, are available from the factory. Contact the factory for information regarding media tolerance in your application.

Figure 3 shows the recommended decoupling circuit for interfacing the output of the integrated sensor to the A/D input of a microprocessor or microcontroller. Proper decoupling of the power supply is recommended.

Figure 4 shows the sensor output signal relative to differential pressure input. Typical, minimum and maximum output curves are shown for operation over a temperature range of 0°C to 85°C using the decoupling circuit shown in Figure 3. The output will saturate outside of the specified pressure range.

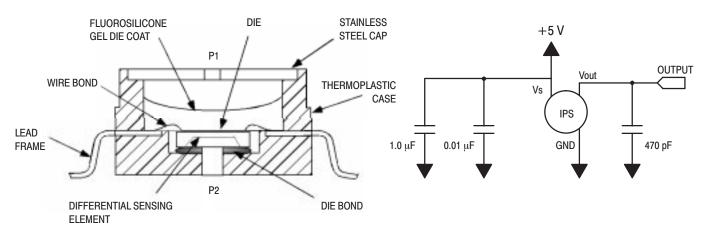


Figure 2. Cross-Sectional Diagram (Not to Scale)

Figure 3. Recommended power supply decoupling and output filtering.

For additional output filtering, please refer to Application Note AN1646.

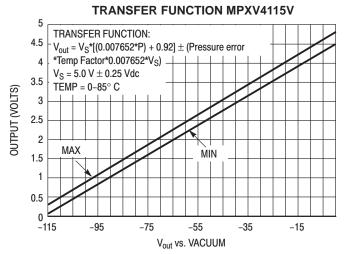


Figure 4. Applied Vacuum in kPa (below atmospheric pressure)

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ORDERING INFORMATION

The MPXV4115V series pressure sensors are available in the basic element package or with a pressure port. Two packing options are also offered.

Device Type	Case No.	Packing Options	Device Marking
MPXV4115V6U	482	Rails	MPXV4115V
MPXV4115V6T1	482	Tape and Reel	MPXV4115V
MPXV4115VC6U	482A	Rails	MPXV4115V

MINIMUM RECOMMENDED FOOTPRINT FOR SURFACE MOUNTED APPLICATIONS

Surface mount board layout is a critical portion of the total design. The footprint for the surface mount packages must be the correct size to ensure proper solder connection interface between the board and the package. With the correct fottprint, the packages will self align when subjected to a solder reflow process. It is always recommended to design boards with a solder mask layer to avoid bridging and shorting between solder pads.

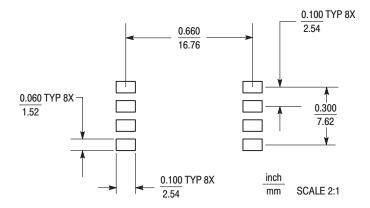
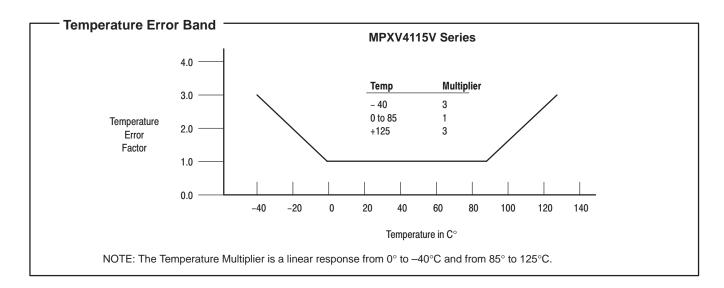


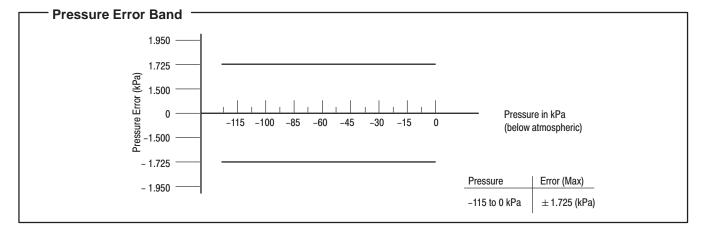
Figure 5. SOP Footprint (Case 482)

Transfer Function

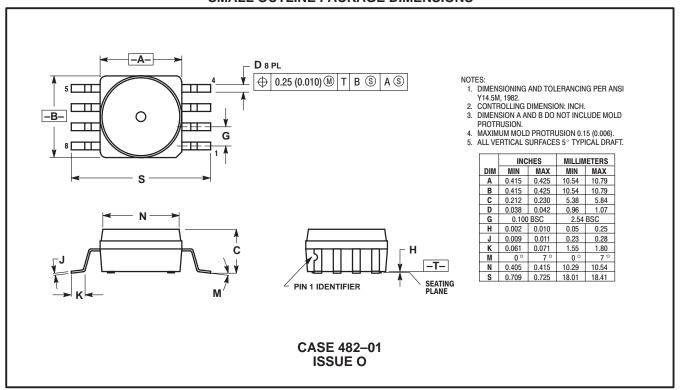
Nominal Transfer Value: $V_{out} = V_S (P \times 0.007652) + 0.92$ +/- (Pressure Error x Temp. Factor x 0.007652 x V_S)

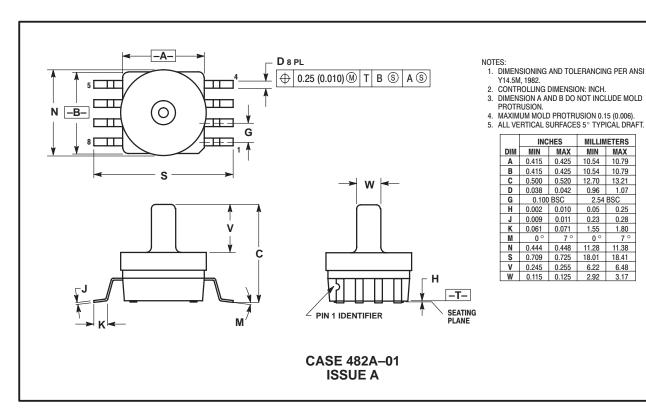
 $V_S = 5 V \pm 0.25 Vdc$





SMALL OUTLINE PACKAGE DIMENSIONS





1.80

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